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dynamics formula  
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$U_1 - 2 = F \cos \alpha \Delta x$ . Work  
of the weight.  $U_1 - 2$   
 $= -W \Delta y = -W(y_2 - y_1)$

Work of the force  
exerted by a spring. (x

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Rectilinear, continuous  
motion: Path is a  
straight line.  $s(t)$   
consists of only one

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PLTW, Inc. Engineering

Formulas  $T F =$

Efficiency  $d = d 00$

Energy: Work  $W =$

work  $F =$  force  $d =$

distance Fluid

Mechanics 1 T ' L



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Power (Guy-L' L P 1 V  
1 = P 2 V 2 B y ' L Q =  
Av A 1 v 1 = A 2 v 2 +  
V absolute pressure =  
gauge pressure +  
atmospheric pressure P  
= absolute pressure  
Force A = Area V =  
volume T T = absolute  
temperature Q = flow  
...

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(6.3) F = force w w  
Numbers Less Than  
One Numbers Greater  
Than One Power of 10  
Decimal Equivalent  
Prefix Abbreviation  
Power of 10 Whole  
Number Equivalent  
Prefix Abbreviation  
10<sup>-1</sup> 0.1 deci- d 10<sup>1</sup> 10  
deca- da 10<sup>-2</sup> 0.01  
centi- c 10<sup>2</sup> 100 hecto-  
h 10<sup>-3</sup> 0.001 milli- m  
10<sup>3</sup> 1000 kilo- k

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PHYS 2310 Engineering  
Physics I Formula

Sheets Chapters 1-18

Chapter 1/Important

Numbers Chapter 2

Units for SI Base

Quantities Quantity

Unit Name Unit Symbol

Length Meter M Time

Second s Mass (not

weight) Kilogram kg

Common Conversions 1

kg or 1 1m 1000 g or m

1 m  $\Delta \times 10^6$  1 m 100

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cm 1 inch 2.54 cm

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How to Solve Problems  
in Mechanics Draw a  
diagram showing  
schematically the  
various parts of the  
assembly of bodies,  
the links, supports, etc.  
Choose a convenient  
part of the assembly as  
one system.

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ME101: Engineering  
Mechanics Mechanics:  
Oldest of the Physical  
Sciences Archimedes  
(287-212 BC):

Principles of Lever and  
Buoyancy! Mechanics  
is a branch of the  
physical sciences that  
is concerned with the  
state of rest or motion  
of bodies subjected to  
the action of forces.

Rigid-body Mechanics

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Dynamics Deformable-  
Body Mechanics, and

## **ME 101: Engineering Mechanics**

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Dynamics Formula  
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Mechanics Rectilinear,  
continuous motion:

Engineering

Mechanics: Dynamics \*

Dr. Yiheng Wang  $s(t)$

consists of only one

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equation. Path is a straight line.  
Rectilinear, erratic motion:  $s(t)$  consists of multiple equations.  
Speed: the magnitude of ...

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Mechanics and  
Machine Design,  
Equations and  
Calculators, Design of  
Load Carrying Shaft



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With One Pulley &  
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Bearings, Flywheel  
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of Inertia, Lifting Boom,  
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Large and Small  
Diameter Lifting Pulley  
/ Drums, Two Lifting  
Lifting Pulley's  
Mechanical Advantage,  
Multiple Pulley's Lifting  
Mechanical Advantage  
Mechanical ...

**Mechanics and**  
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81

**Engineering Fluid  
Mechanics -  
Staffordshire  
University**

F13-1. The motor winds in the cable with a constant acceleration, such that the 20-kg crate moves a distance  $s = 6$  m in 3 s, starting from rest. Determine the tension developed in the cable. The

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coefficient of kinetic  
friction between the  
crate and

## **(PDF) Engineering Mechanics for Preparatory Year Spring ...**

In this Live session,  
Deep sangeet will  
Discuss the newly  
added chapter in  
engineering mechanics  
i.e. Lagrange's  
equation.

## **Lagrange's Equation**

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Basic Mechanics of  
Materials: Computing  
Stresses in Columns.  
Knowing how to  
compute the stress in a  
column (compression  
member) is a basic  
point of knowledge in  
mechanics of  
materials. Determine if  
the column is ' short,  
slender, or  
intermediate by  
computing its

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maximum slenderness ratio ( $KL/r$ ). For short columns, the stress of a member in compression is the basic axial stress formulation.

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Formula sheet. Fluid Mechanics key facts (1/5) ... • Familiarize yourself with the fluid mechanics section of the formula sheet • Try questions from the



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## **Revision : Fluid mechanics**

Classical mechanics is  
the branch of physics  
used to describe the  
motion of macroscopic  
objects. It is the most  
familiar of the theories  
of physics. The

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concepts it covers, such as mass, acceleration, and force, are commonly used and known. The subject is based upon a three-dimensional Euclidean space with fixed axes, called a frame of reference.

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