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The approach consists of two main phases, the first phase executes a clustering algorithm on local data, assuming that the datasets was already distributed among the system processing nodes.

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The last section explains the complete Paxos algorithm, which is obtained by the straightforward application of consensus to the state machine approach for building a distributed system—an approach that should be well-known, since it is the subject of what is probably the most often-cited article on the theory of distributed systems [4]."

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world protocols, the BMC algorithm (a key component of the IEEE 1588 standard), and the time synchronized channel hopping protocol (Sec. 6). 2 Formal Model and Approach In this section, we define clock synchronization precisely and formalize the notion of symmetric almost-synchronous (SAS) systems, the class of distributed systems we are

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